

### Test Procedure for the STK681-300GEVB Evaluation Board

#### **Evaluation Board Setup**

[Supply Voltage] Vcc1 (10 to 42V): Power Supply for DC motor Vcc2 (5V) : Power Supply for internal logic IC

#### [Operation Guide]

1. Motor Connection:

Connect the motor to OUT1 and OUT2.

2. Initial Condition Setting:

Set to signal condition IN1=H, IN2=H, and INH=L.

3. Power Supply:

At first, supply DC voltage to Vcc2(5.0V). Next, supply DC voltage to Vcc1.

4. Set to Forward or Reverse signal condition with INH=Low.

Turn "High" INH signal.

Output current flows between OUT1 and OUT2.

5. Motor Operation

[Setting the current limit using the Vref pin]

Without external resistance R3, output current is limited to Iomax.

You can limit to below lomax by installing R3.

As for Iomax of STK681-310, 0.42V is generated with 5V, internal resistance 82k (R1) and 7.5k (R2), then Iomax=4.2A is designed by comparing with internal current sensing resistor Rs.

In case of without external resistance R3 Iomax=(Vcc2×R2/(R1+R2))÷Rs

R1 R2 Rs STK681-300 82kΩ 5.1kΩ 0.1Ω STK681-310 82kΩ 7.5kΩ 0.1Ω STK681-320 82kΩ 5.1kΩ 0.056Ω

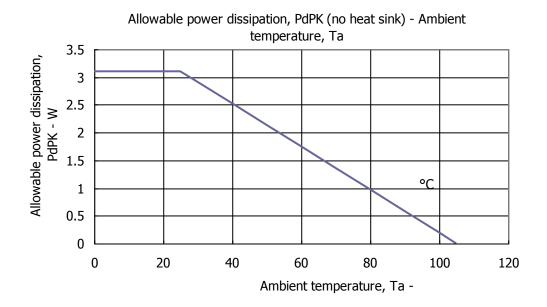
Including external resistance R3

 $lo = ((Vcc2x(R2xR3)/(R2+R3))/(R1+(R2xR3)/(R2+R3))) \div Rs$ 

If you mount external resistor R3=7.5k, for instance, you can limit to 2.1A, which is half of lomax (4.2A) of STK681-310.

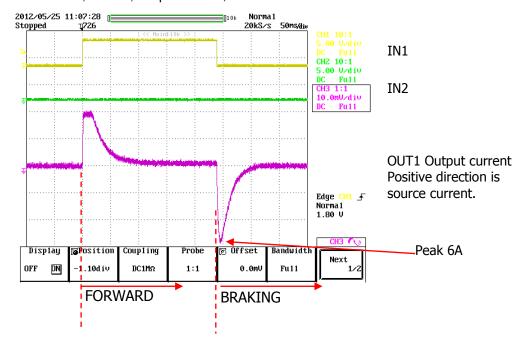


### Allowable power dissipation (Reference value)



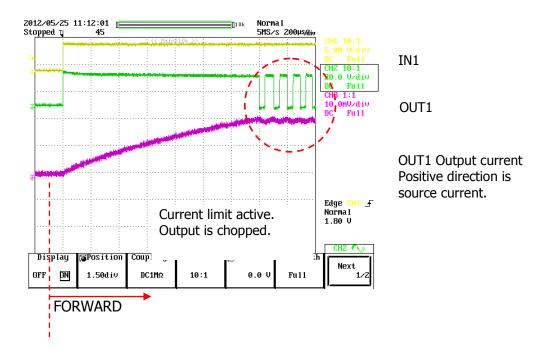
### Waveform example

## STK681-310(Current limit 4.2A setting) IN1 and IN2; 5V/div, Output current; 2A/div





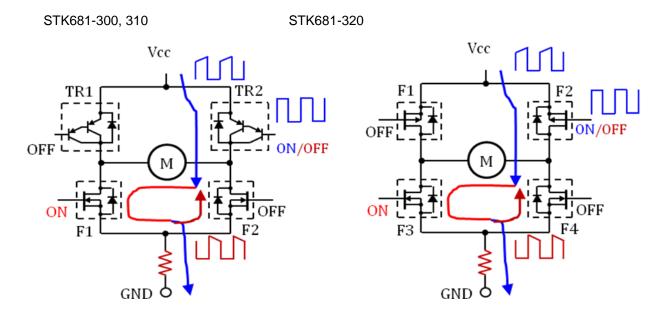
STK681-310(Current limit 2A setting)
IN1 5V/div, OUT1 20V/div, Output current; 2A/div



Current control is slow decay.

STK681-300, 310 and 320 control Bipolar Transistor or MOSFET at High side by constant-current PWM control system.

Current control enters Slow decay mode.





# STK681-310(Current limit 4.2A setting) IN1 and IN2; 5V/div, Output current; 2A/div

